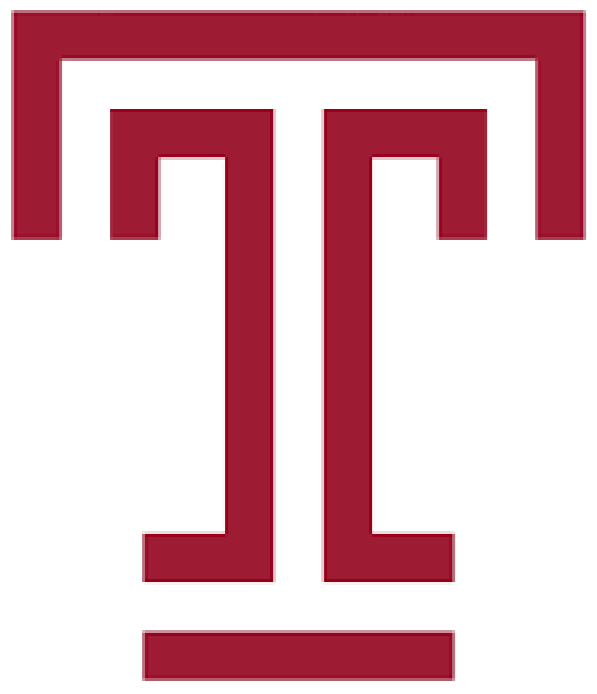


Generalization-Aware Structured Regression towards Balancing Bias and Variance



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Abstract

Attaining the proper balance between underfitting and overfitting is one of the central challenges in machine learning. It has been approached mostly by deriving bounds on generalization risks of learning algorithms. Such bounds are, however, rarely controllable. In this study, a novel bias-variance balancing objective function is introduced in order to improve generalization performance. By utilizing distance correlation, this objective function is able to indirectly control a stability-based upper bound on a model's expected true risk. In addition, the Generalization-Aware Collaborative Ensemble Regressor (GLACER) is developed, a model that bags a crowd of structured regression models. Allowing its base components to collaborate in a fashion that minimizes the proposed objective function, GLACER has shown to outperform a broad range of both traditional and structured regression models, while sustaining stable predictions.

The Notion of Generalization

• **Intuition:** Striking the proper balance between *underfitting* and *overfitting*
⇒ A fundamental challenge in supervised learning

• Underfitting

- high **bias**
- Avoided by **reducing** the empirical risk R_{emp}

• Overfitting

- high **variance**
- Reduces as the *empirical risk* (training error) becomes a **valid estimate** of the *true unknown risk* (test error):

$$R_{gen} = |R_{emp} - R_{true}|$$

• **Objective:** Minimize R_{emp} , while maintaining low R_{gen}

Main Theoretical Insight

- R_{emp} can be easily minimized since it is “**measurable**” from the observed data
- R_{gen} is often **impossible to determine** since R_{true} is unknown
- But, there are **stability-based upper bounds** derived on the *expected true risk* [1,2]:

$$\hat{R}_{true}(\mathcal{L}) \leq \underbrace{\mathbb{E}_{\mathcal{D}}[\mathbb{E}_{h|\mathcal{D}}[R_{emp}(h, \mathcal{D})]]}_{\text{Expected empirical risk of a hypothesis } h \text{ w.r.t. a training set } \mathcal{D}} + \underbrace{1 - \mathcal{S}(\ell(\cdot, h), z_{trn})}_{\text{Mutual stability between the loss of } h \text{ and a random training example } z_{trn}} \quad (*)$$

• Design of a **bias-variance balancing objective function**

$$R_{obj}(h, \mathcal{D}) = \sqrt{R_{emp}(h, \mathcal{D})^2 + dCorr(\ell(\cdot, h), z_{trn})^2}$$

• **Aims to tighten the upper bound (*)** by:

- 1) **minimizing** the **empirical risk** $R_{emp}(h, \mathcal{D})$
- 2) utilizing **distance correlation** [3,4] to make the loss w.r.t. to given data as independent as possible of the data themselves and thus to indirectly control the **mutual stability term**

Note: $R_{obj}(h, \mathcal{D})$ is defined for a hypothesis h selected by **any supervised learning algorithm** \mathcal{L}
⇒ In this study, this objective is utilized in a **structured regression** setting.

Methodology

Structured Regression by Gaussian CRFs

A Gaussian CRF (GCRF) models the conditional distribution:

$$P(y|\mathbf{X}) = \frac{1}{Z} \exp \left\{ -\alpha \sum_{i=1}^N (y_i - \phi(\mathbf{x}_i))^2 - \beta \sum_{i \sim j} S_{ij} (y_i - y_j)^2 \right\}$$

Proposed Model

Generalization-Aware Collaborative Ensemble Regressor (**GLACER**)

Input:

Training set \mathcal{D}
Similarity matrix \mathbf{S}
of components M
Sub-sampling fraction η

Sample \mathcal{D} and \mathbf{S} (omitted for brevity) M times without replacement using the sub-sampling fraction η

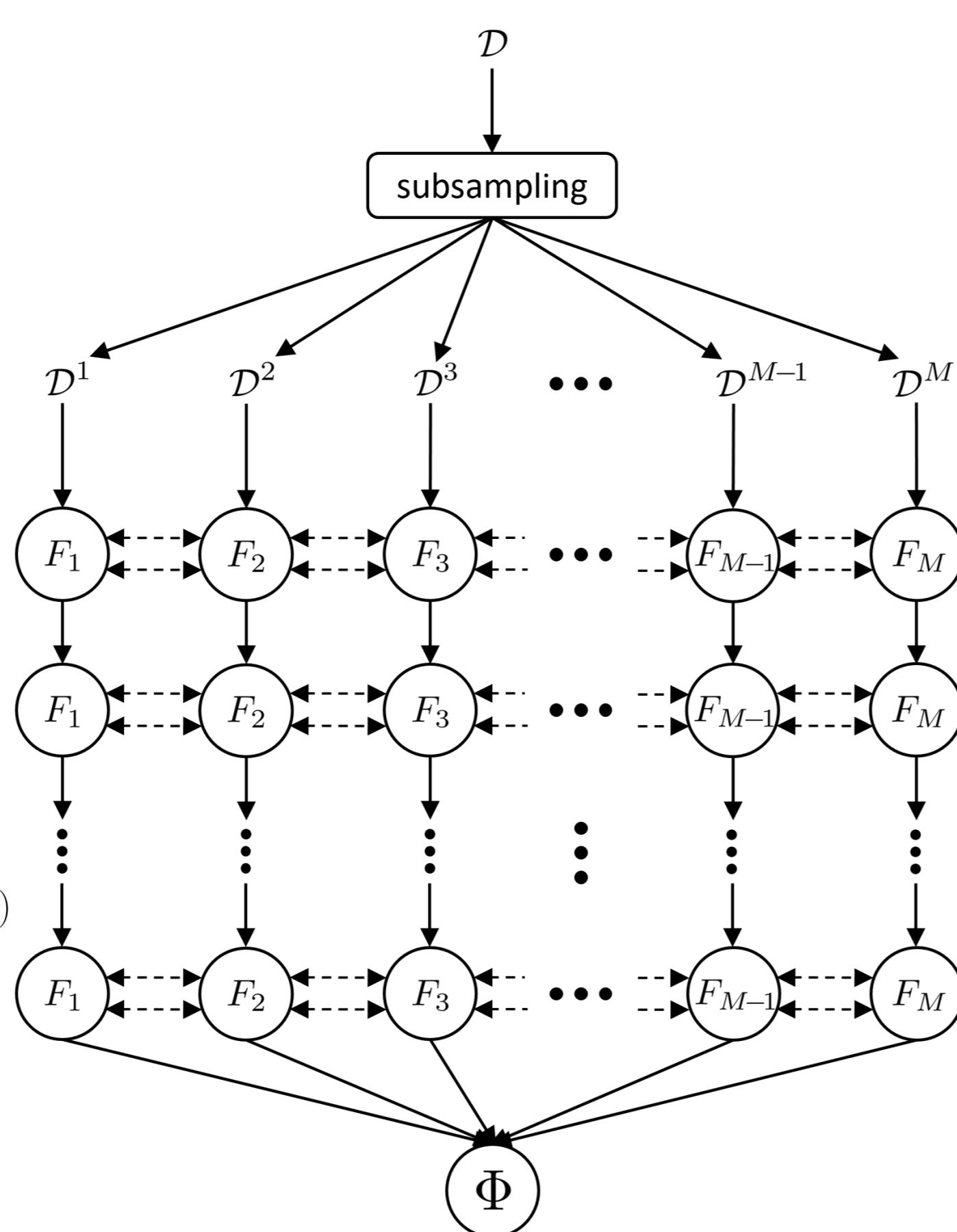
Train a single GCRF component F_m (on top of a least-squares booster) on each \mathcal{D}^m and its corresponding \mathbf{S}^m

Loop

- **determine** the **worst-fit** example for each component
- **exchange** the worst-fit examples between the pair of GCRFs that fosters the highest decrease in $R_{obj}(\Phi, \mathcal{D})$

Repeat until no exchange can further decrease $R_{obj}(\Phi, \mathcal{D})$

Prediction: $\Phi(\mathbf{X}, \mathbf{S}) = \frac{1}{M} \sum_{m=1}^M F_m(\mathbf{X}, \mathbf{S})$



Results

Experiments on Synthetic Data

- **Examples:** 3000 input-output pairs
 - input features: normally distributed
 - outputs: parameterized polynomials with uniformly distributed parameters
- **Structure:** generated using an Erdős-Rényi random graph model

Experiment #1: Generalization Capability

- In general, structured variants perform better than unstructured
- While the baselines' MSEs decrease with the increased size of training data, GLACER is more accurate and sustains stable predictions when only 50% training data is available
- ⇒ This is consistent in case smaller/larger training fractions are used

Experiment #2: Influence of $dCorr$

R_{obj} Frac.	Without $dCorr$	With $dCorr$
10%	0.74	0.72
50%	0.44	0.25
100%	0.53	0.25

Average testing MSE, obtained before and after using $dCorr$ within R_{obj} .

- GLACER manifests lower average MSEs when $dCorr$ is used in R_{obj}
⇒ This is consistent as the training data increases
- Without $dCorr$, the avg. MSE deteriorates once the training fraction increases from 50% to 100%
⇒ Might be an indication of overfitting
- Incorporating $dCorr$ into R_{obj} prevents large increases in MSE

Sacramento Real-Estate

• **Nodes:** 985 real estate transactions were observed in the Greater Sacramento area

• **Features:** # of bedrooms and bathrooms, house area in square feet, location in terms of latitude and longitude

• **Structure:** based on geospatial similarity

• **Train/test** ratio used is the same as in [5]

Task: predict the housing prices

Model \ Frac.	50%
Linear Reg.	2.3 ± 0.05
Structured Linear Reg.	1.5 ± 0.05
Neural Network	1.4 ± 0.21
Structured Neural Network	1.0 ± 0.18
Support Vector Reg.	2.4 ± 0.12
Structured Support Vector Reg.	1.8 ± 0.12
Subbagging	1.3 ± 0.01
Structured Subbagging	0.9 ± 0.03
Random Forest	1.6 ± 0.05
Structured Random Forest	1.4 ± 0.03
LS Boosting	2.8 ± 0.05
Structured LS Boosting	0.9 ± 0.02
Convex Network Lasso	1.2 ± 0.04
Non-convex Network Lasso	1.3 ± 0.05
GLACER	0.3 ± 0.01

Average testing MSE when 50% of the training data is supplied.

Medicare Readmissions

• **Nodes:** 1000 hospital records referring to hospitals with more than ~150 readmissions

• **Features:** # of discharges, excess readmission ratio, estimated/expected readmission rates

• **Structure:** similarities between hospital readmissions

• **Period:** 36 months (July 2012 – June 2015)

Task: predict the number of hospital readmissions

Model	MSE
Linear Reg.	0.507 ± 0.025
Structured Linear Reg.	0.465 ± 0.024
Neural Network	0.516 ± 0.026
Structured Neural Network	0.463 ± 0.023
Support Vector Reg.	0.515 ± 0.031
Structured Support Vector Reg.	0.479 ± 0.034
Subbagging	0.304 ± 0.017
Structured Subbagging	0.262 ± 0.015
Random Forest	0.283 ± 0.020
Structured Random Forest	0.249 ± 0.015
LS Boosting	0.288 ± 0.015
Structured LS Boosting	0.250 ± 0.017
Convex Network Lasso	0.368 ± 0.013
Non-convex Network Lasso	0.380 ± 0.017
GLACER	0.225 ± 0.005

Testing MSE, averaged over 10 random splits.

Model	MSE
Linear Reg.	1755.708 ± 616.119
Structured Linear Reg.	525.551 ± 196.065
Neural Network	2037.421 ± 1199.805
Structured Neural Network	1618.547 ± 1192.462
Support Vector Reg.	1359.342 ± 697.910
Structured Support Vector Reg.	504.076 ± 221.228
Subbagging	441.524 ± 101.065
Structured Subbagging	234.505 ± 74.378
Random Forest	508.294 ± 110.988
Structured Random Forest	247.406 ± 35.814
LS Boosting	595.289 ± 136.174
Structured LS Boosting	182.006 ± 24.919
(Non-)convex Network Lasso	5012.614 ± 768.945
GLACER	73.183 ± 9.032

Testing MSE, averaged over 10 random splits.

GLACER - Discussion:

- **Outperforms alternatives** by ~10-56% and **more than 49%** when predicting housing prices and hospital readmissions, respectively.
- Achieves **statistically significant improvements** ⇒ p -values are smaller than 0.01 for Sacramento, and 0.021 for Medicare.
- Manifests **stable predictions** ⇒ tight confidence interval for its average MSE.

Acknowledgments

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